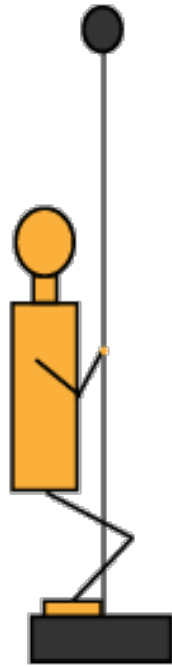


New physical insights in passive dynamical stabilization in time periodic systems

A. Anzoleaga Grandi, S. Protière and A. Lazarus

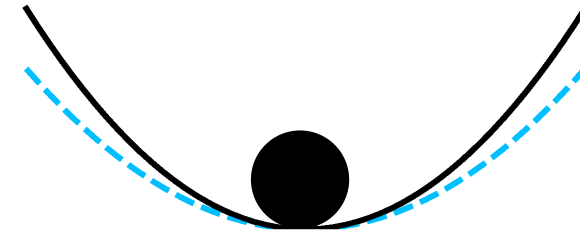
Time-periodic systems

Child on a swing

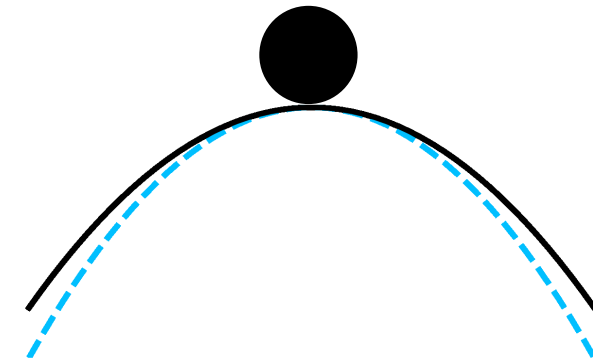


2 parameters {
Period of modulation
Amplitude of modulation

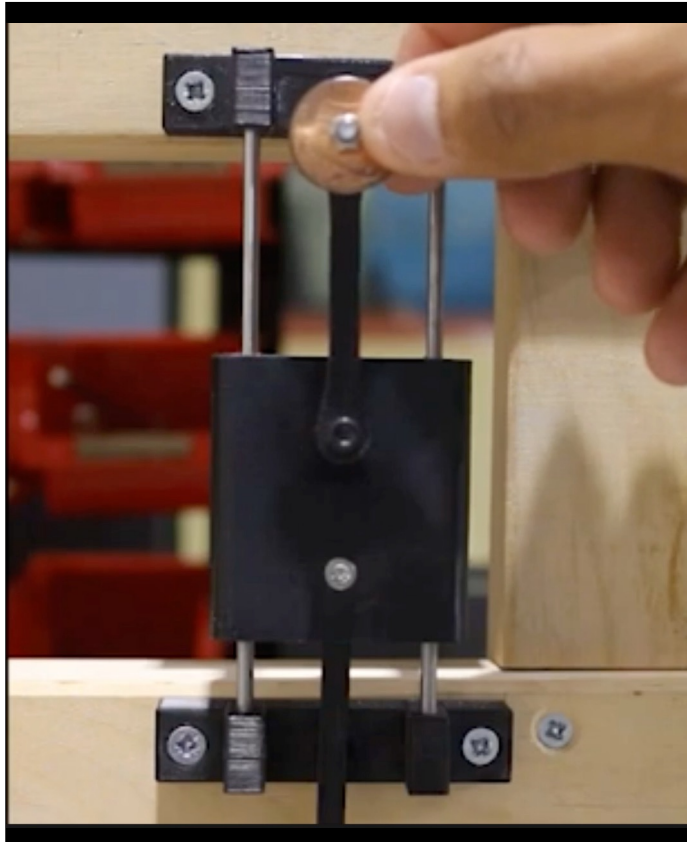
Parametric instabilities



Dynamical stabilization

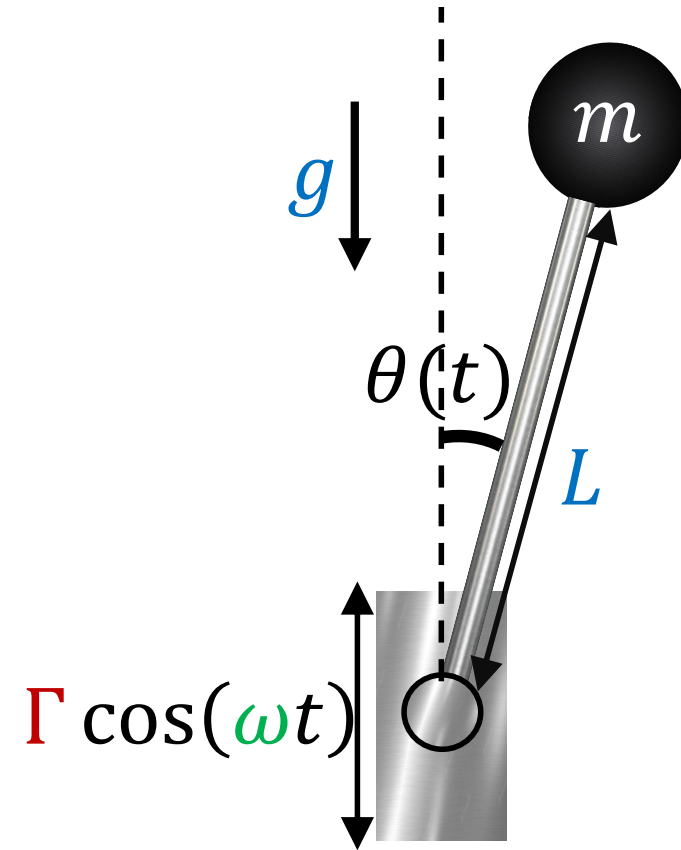


Dynamical stabilization



Dynamical stabilization of the upward position of a pendulum

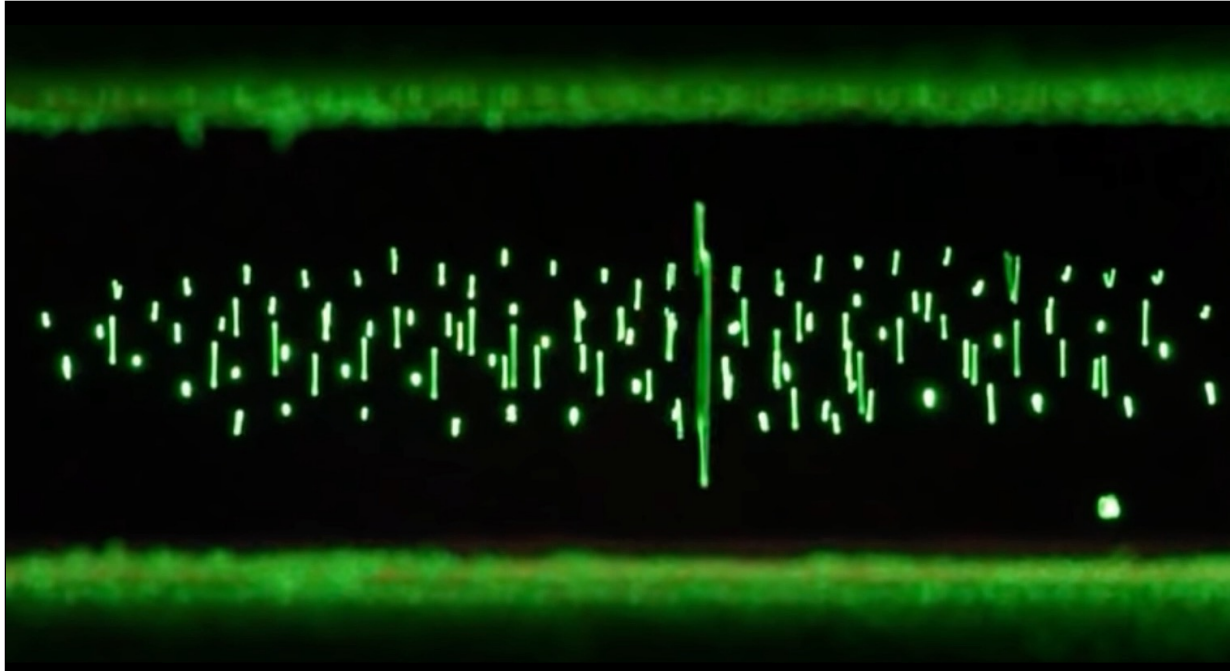
Video credit: University of California



$$\text{Kapitza limit: } \Gamma^2 \omega^2 \geq 2gL$$

P.L. Kapitza, *Sov. Phys. JETP*, 588–597, 1951.

Dynamical stabilization



Paul's Trap: trapping particles in an electric field [1]

Video credit: Newtonian Labs

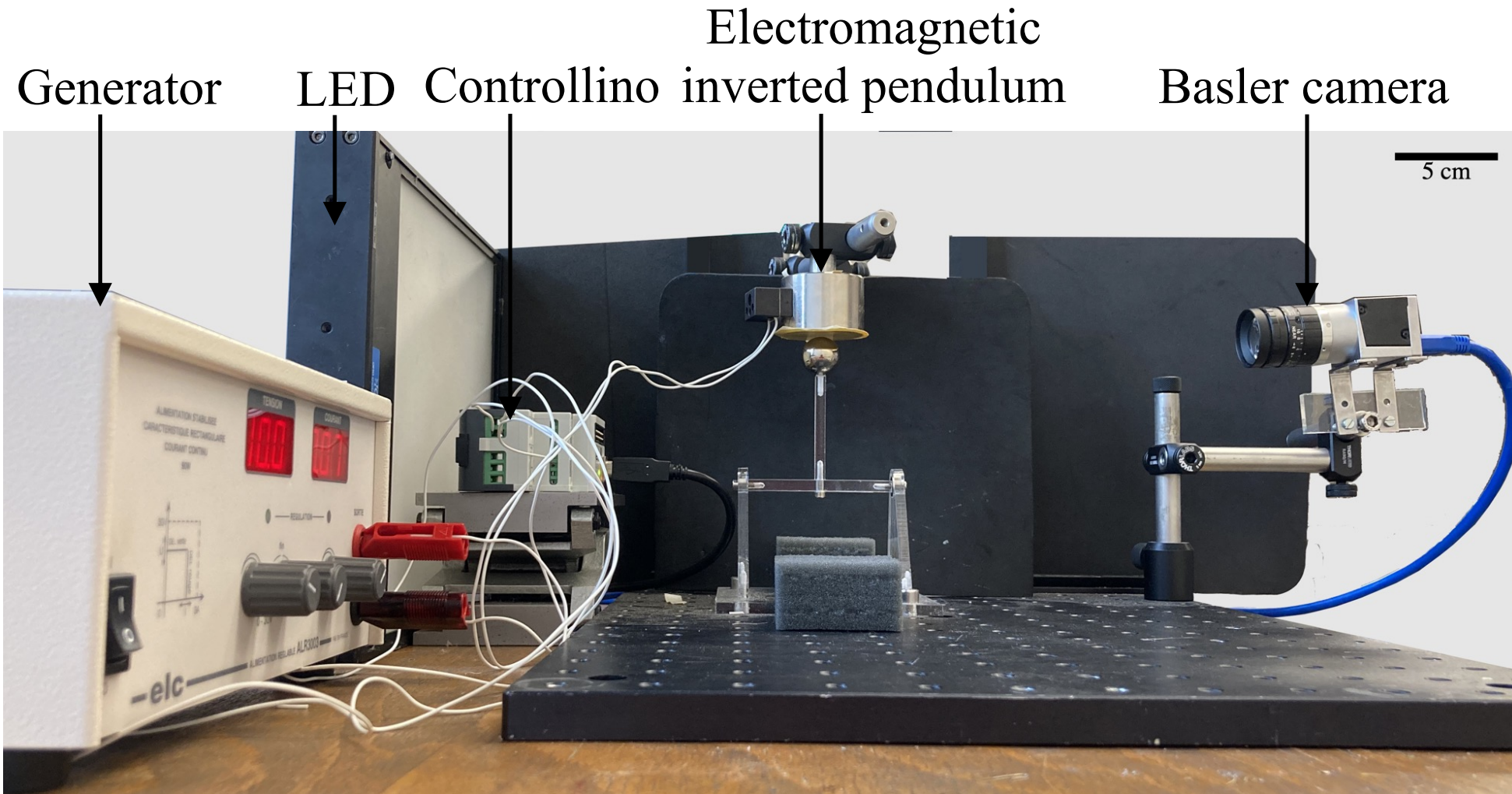


Making two liquid layer levitate [2]

[1] W. Paul. *Reviews of modern physics*, **62**, 1990.

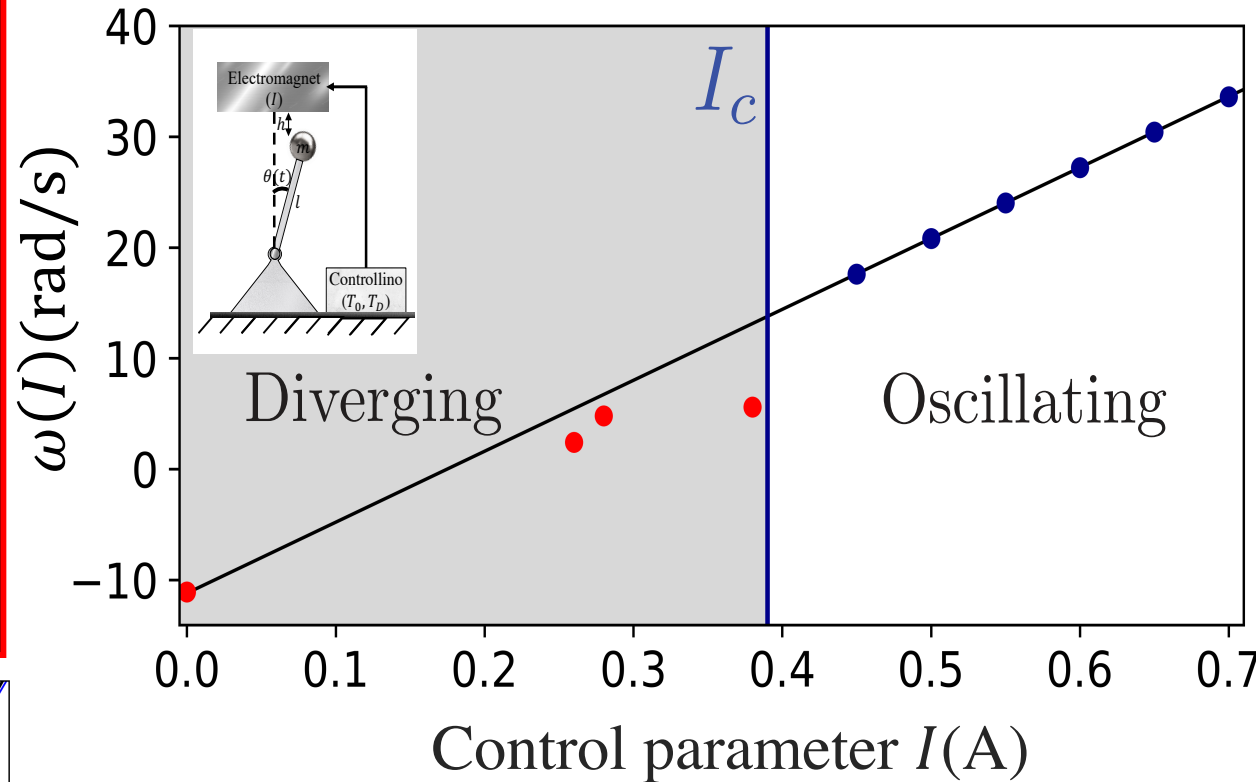
[2] B. Apffel *et al.* *Nature*, **585**, 2020.

Electromagnetic inverted pendulum

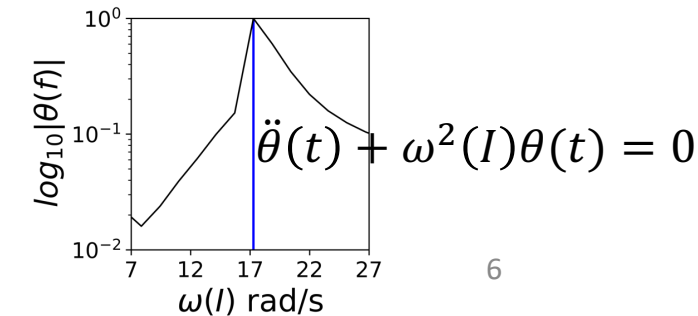
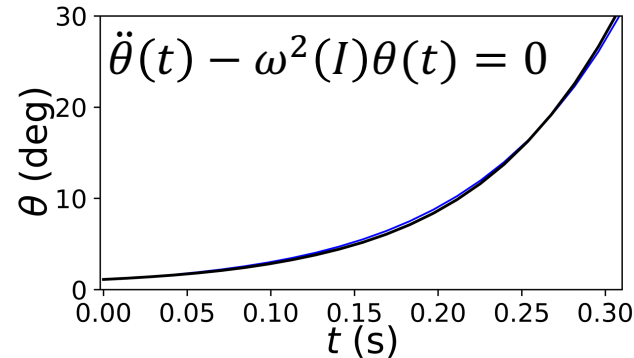
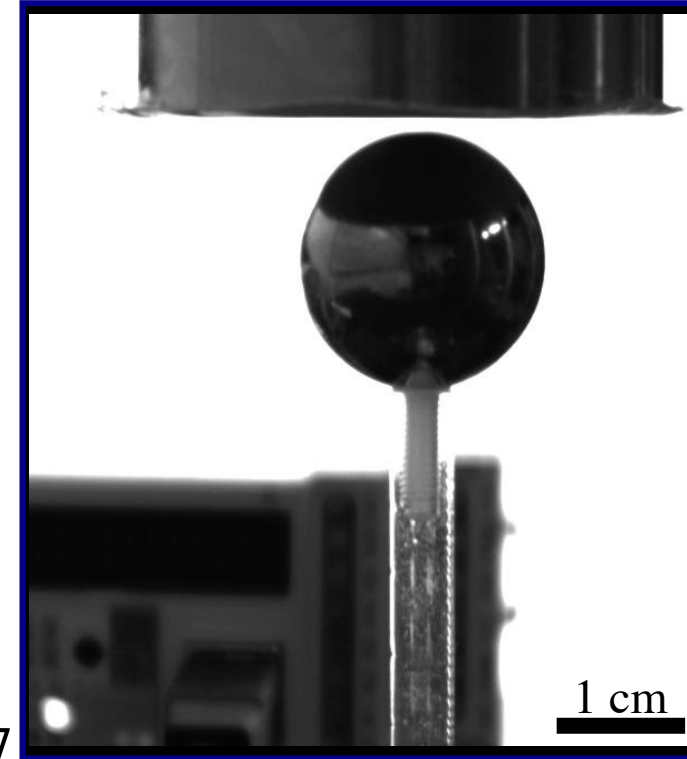


Large modulations at the macroscopic scale

$I = 0 \text{ A}$

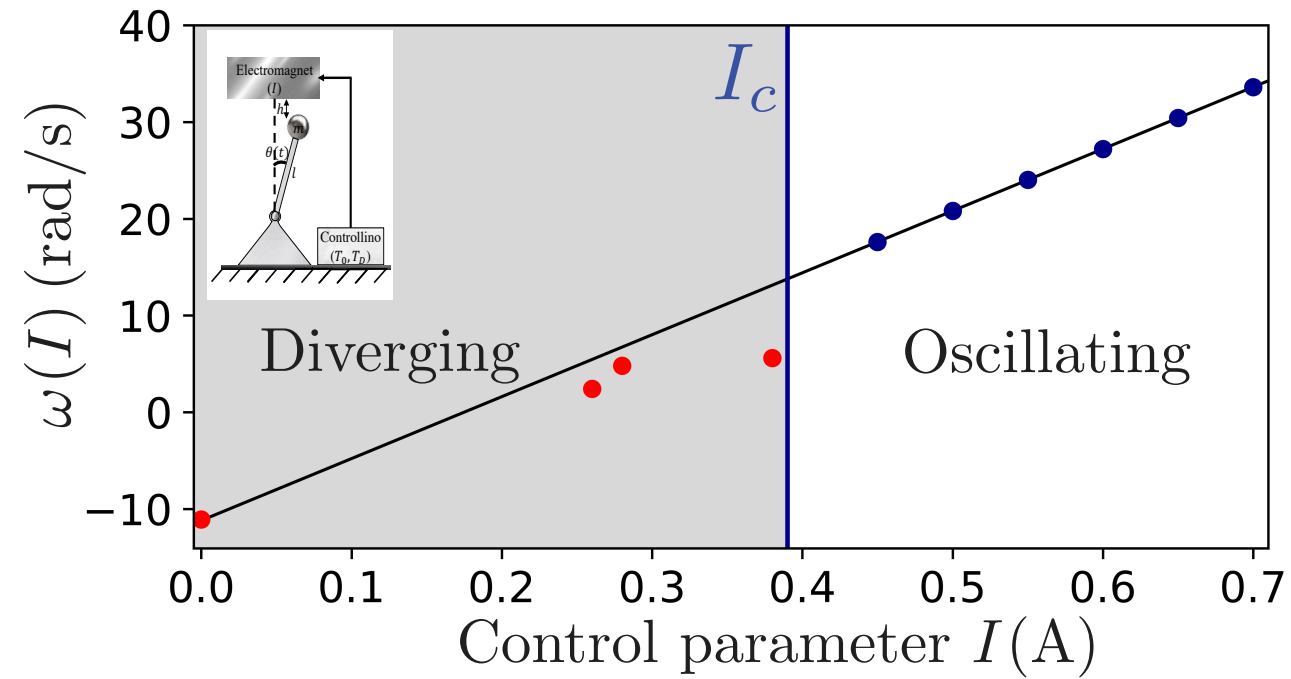
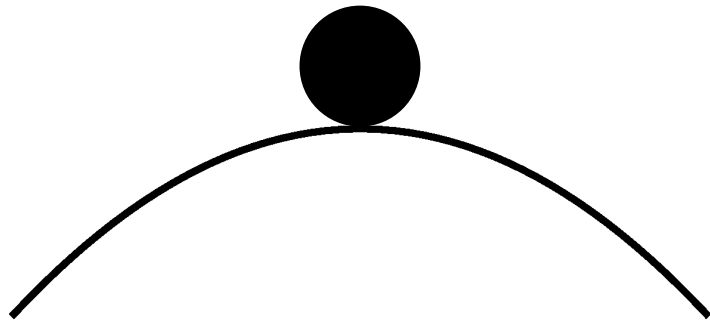
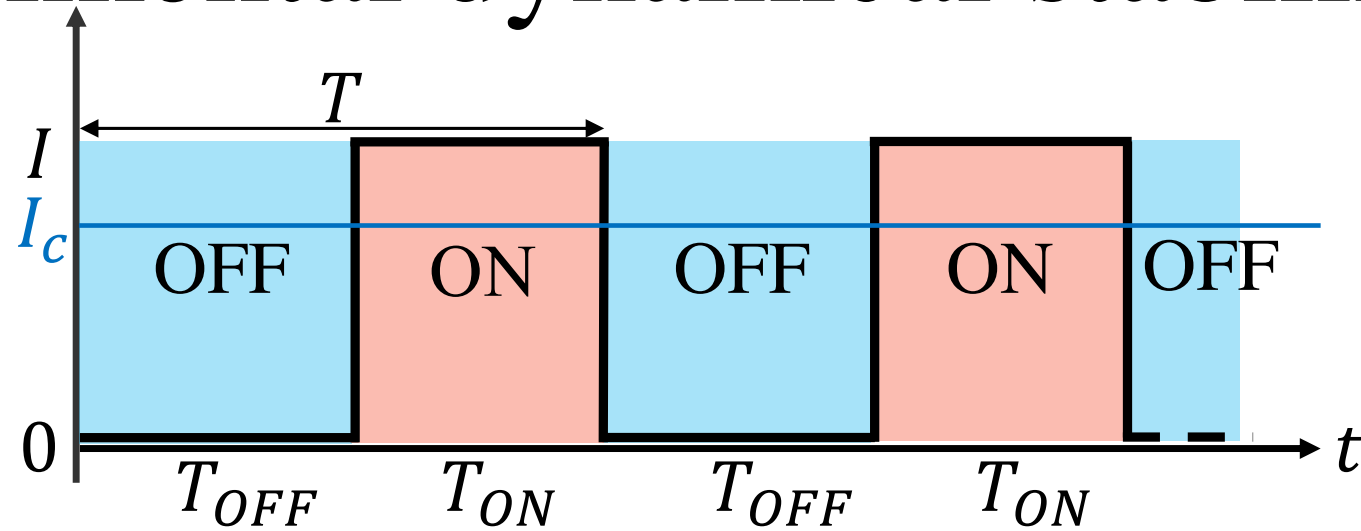


$I = 0.45 \text{ A}$

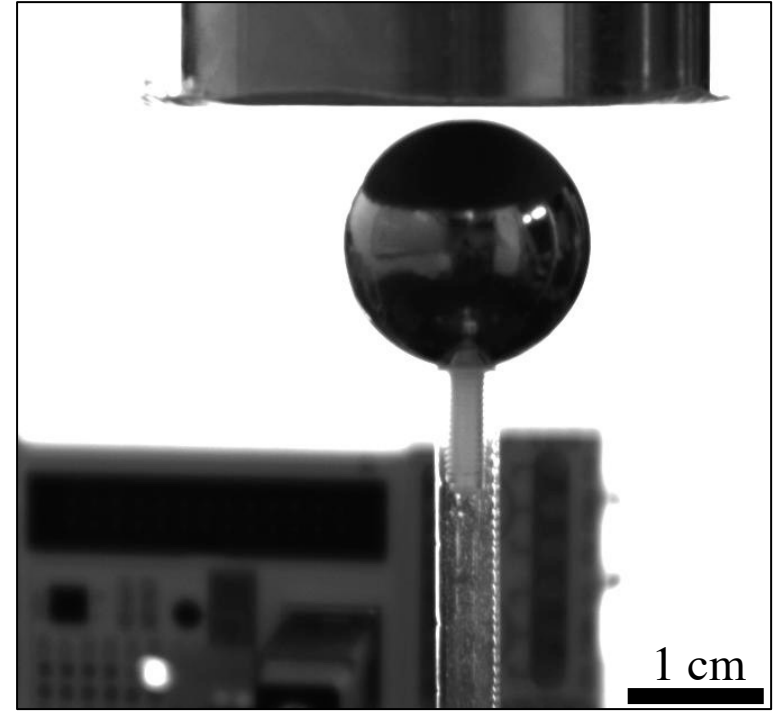
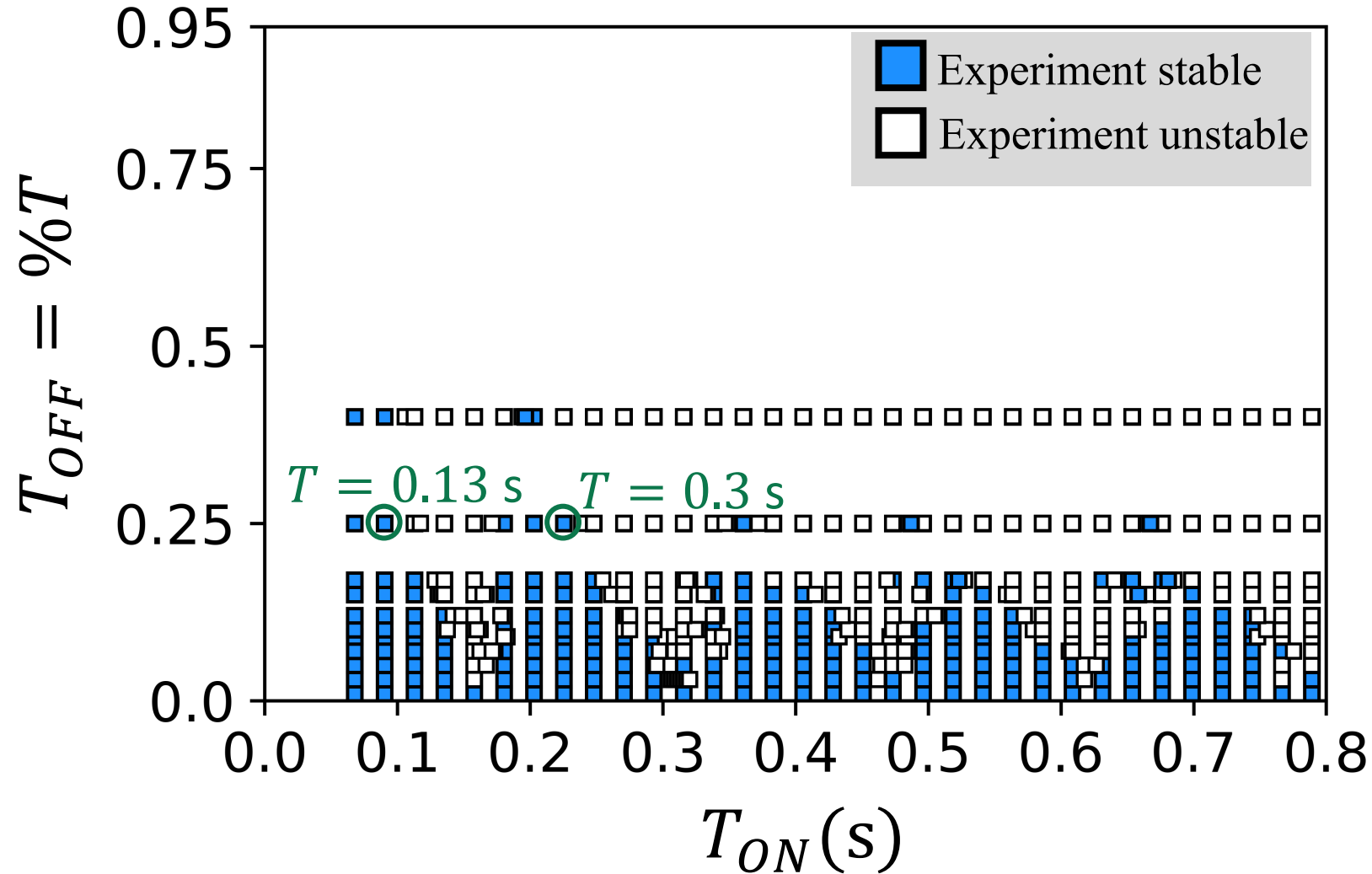


White light = Electromagnets ON

Experimental dynamical stabilization

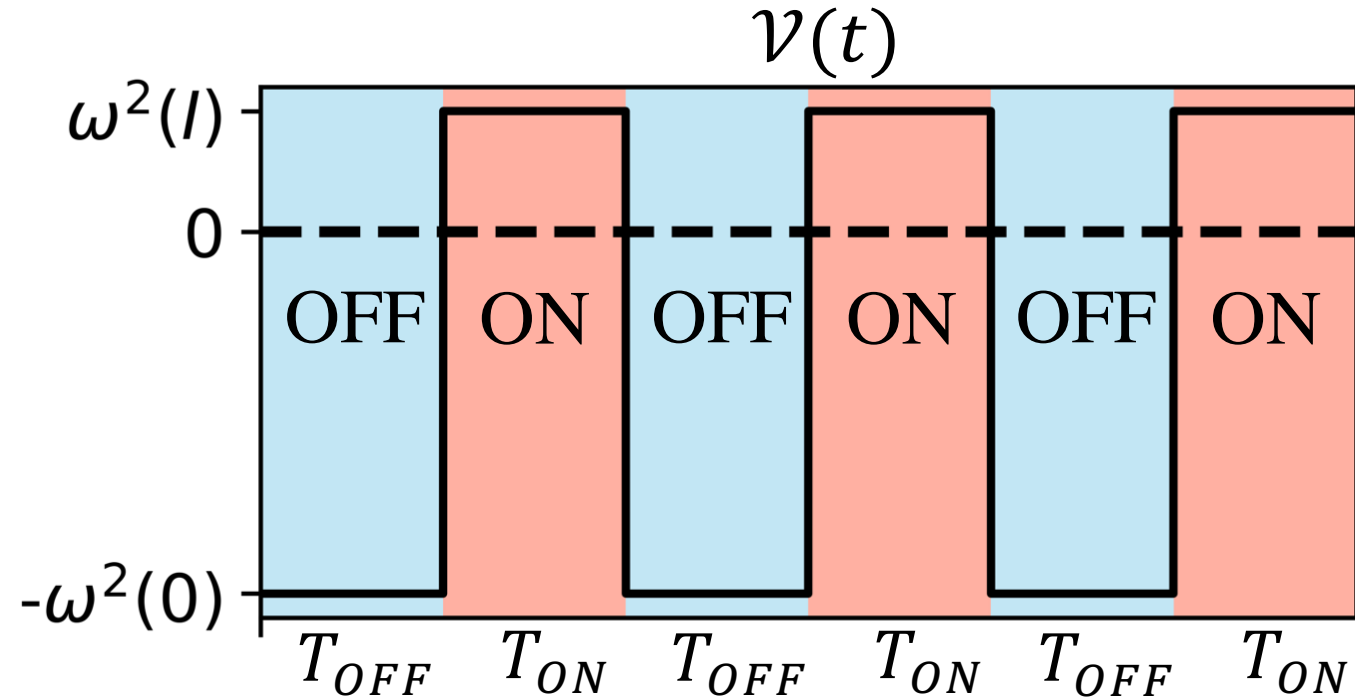
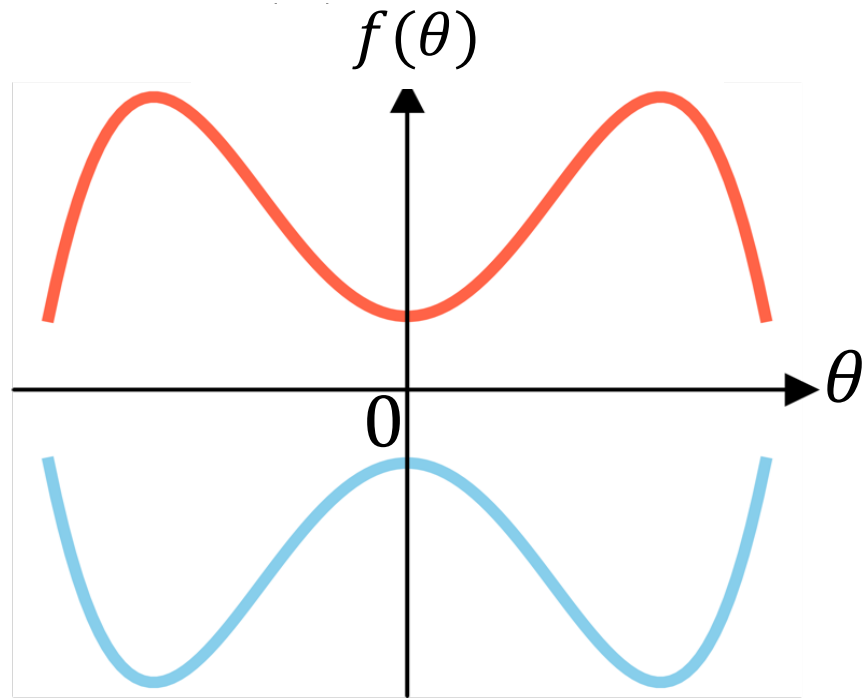


Experimental dynamical stabilization



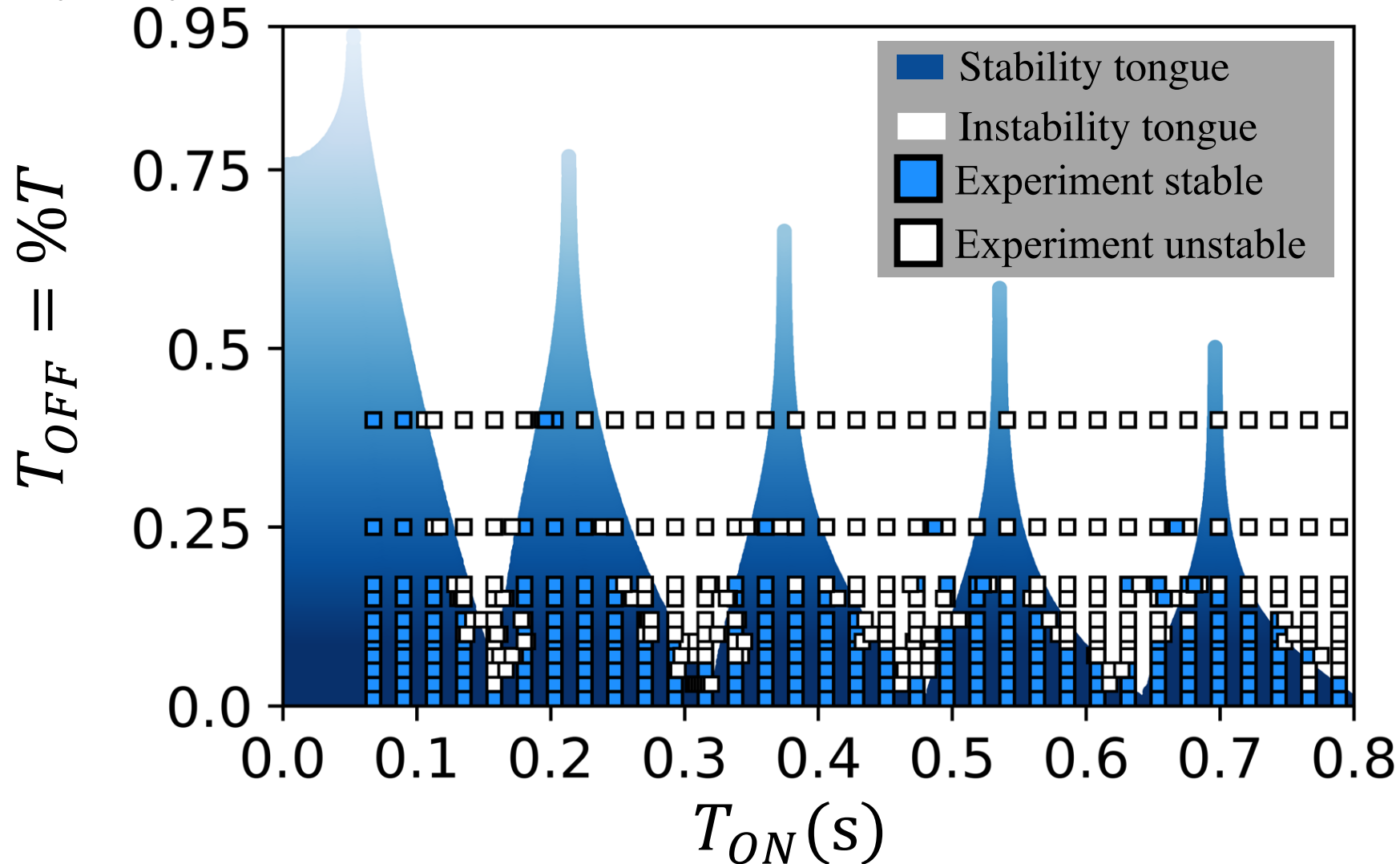
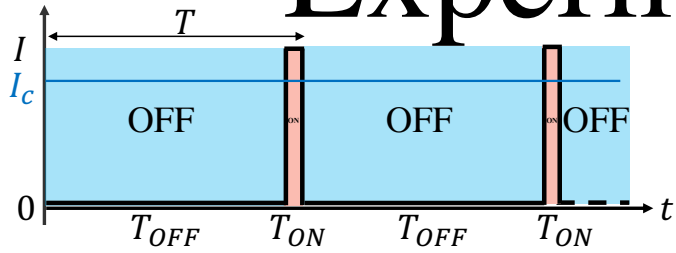
Characteristic time: Inverted pendulum: Smith et. al (1992):
 $T_0 = 0.57 s$ $T_0 = 0.18 s$
 $T = 6.4 \times 10^{-3} s$

Experimental dynamical stabilization



$$\begin{cases} \frac{d^2\theta}{dt^2} - \omega^2(0)\theta(t) = 0 \text{ during } T_{OFF} \\ \frac{d^2\theta}{dt^2} + \omega^2(I)\theta(t) = 0 \text{ during } T_{ON} \end{cases}$$

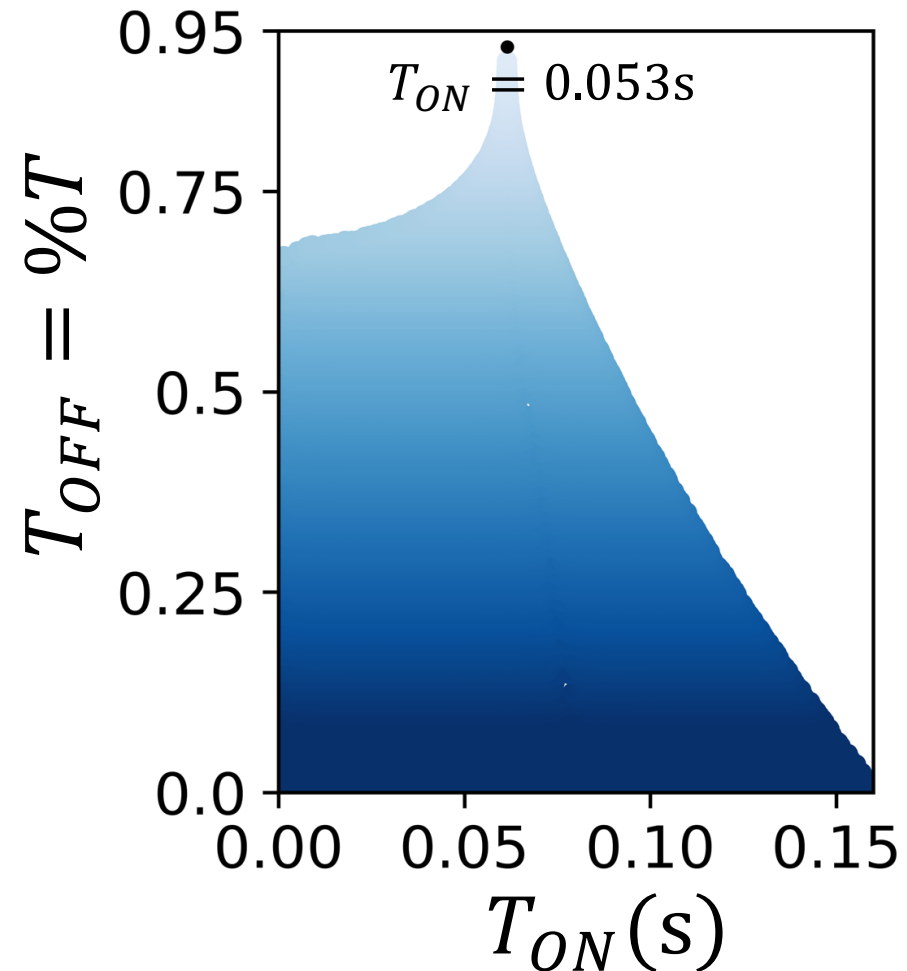
Experimental dynamical stabilization



Numerical study of the tip of the stability regions

$\omega(0) = 11.1$ rad/s and $\omega(I) = 19.5$ rad/s

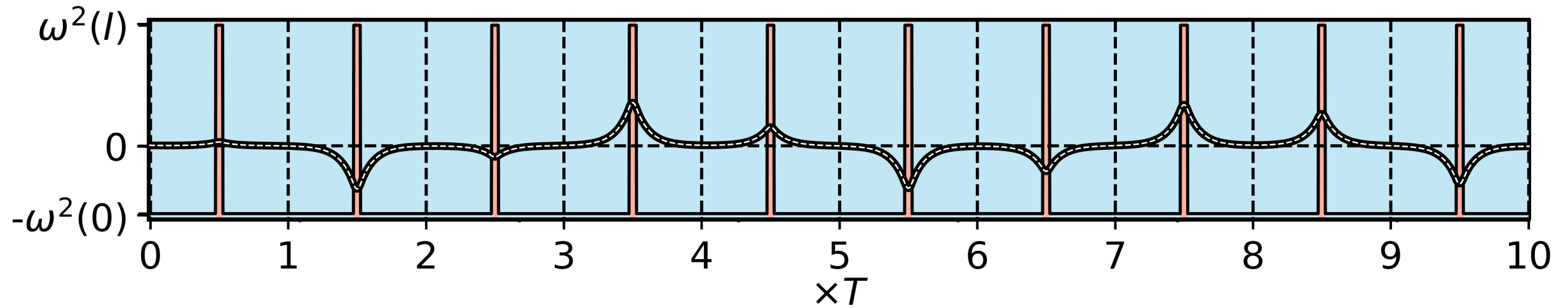
$T_{OFF} = 0.95\%T$



Numerical study of the tip of the stability regions

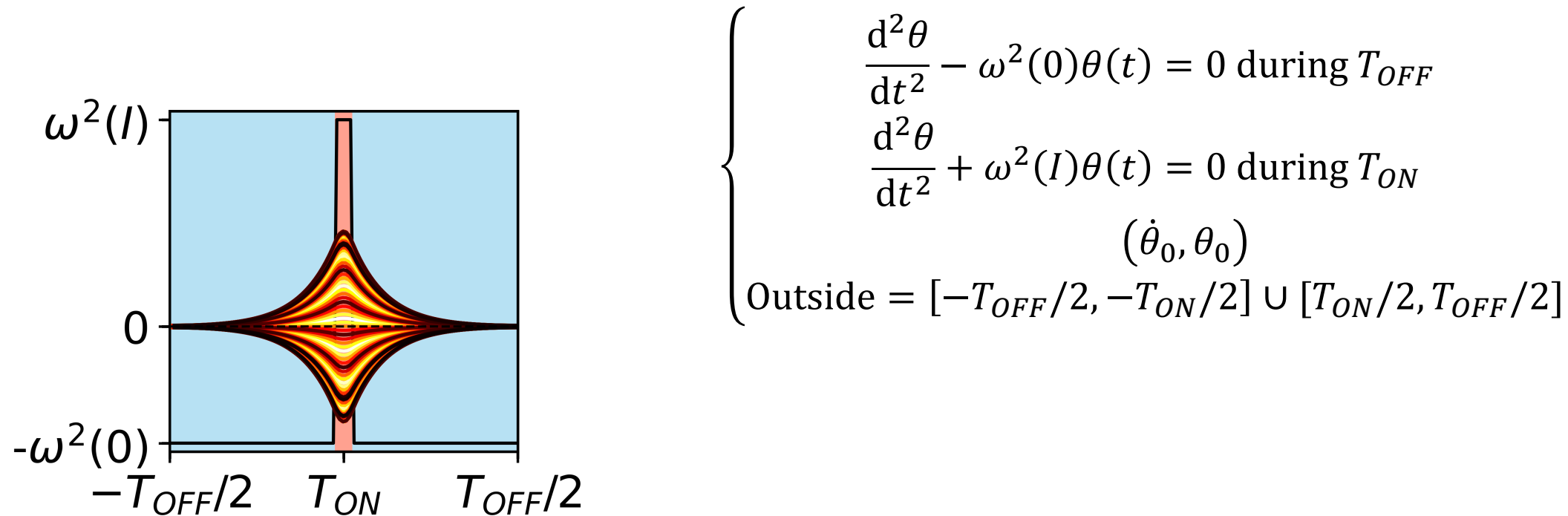
$\omega(0) = 11.1 \text{ rad/s}$, $\omega(I) = 19.5 \text{ rad/s}$, $T_{OFF} = 0.95\%T$ and $T_{ON} = 0.053s$

— Linear response
— Nonlinear response



Numerical study of the tip of the stability regions

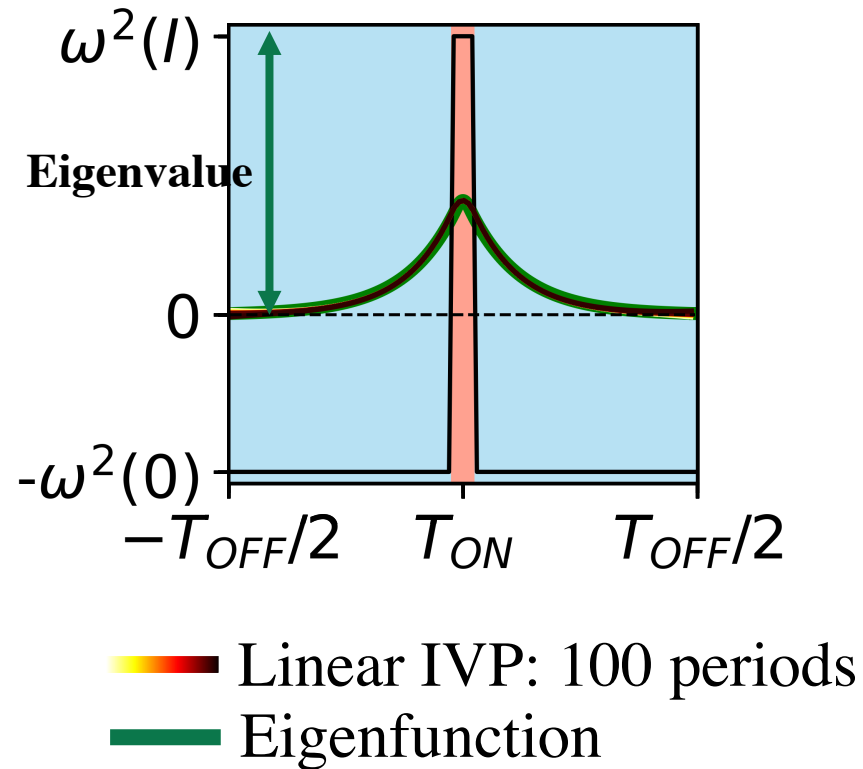
$\omega(0) = 11.1 \text{ rad/s}$, $\omega(I) = 19.5 \text{ rad/s}$, $T_{OFF} = 0.95\%T$ and $T_{ON} = 0.053s$



Linear IVP: 100 periods

Numerical study of the tip of the stability regions

$\omega(0) = 11.1 \text{ rad/s}$, $\omega(I) = 19.5 \text{ rad/s}$, $T_{OFF} = 0.95\%T$ and $T_{ON} = 0.053s$



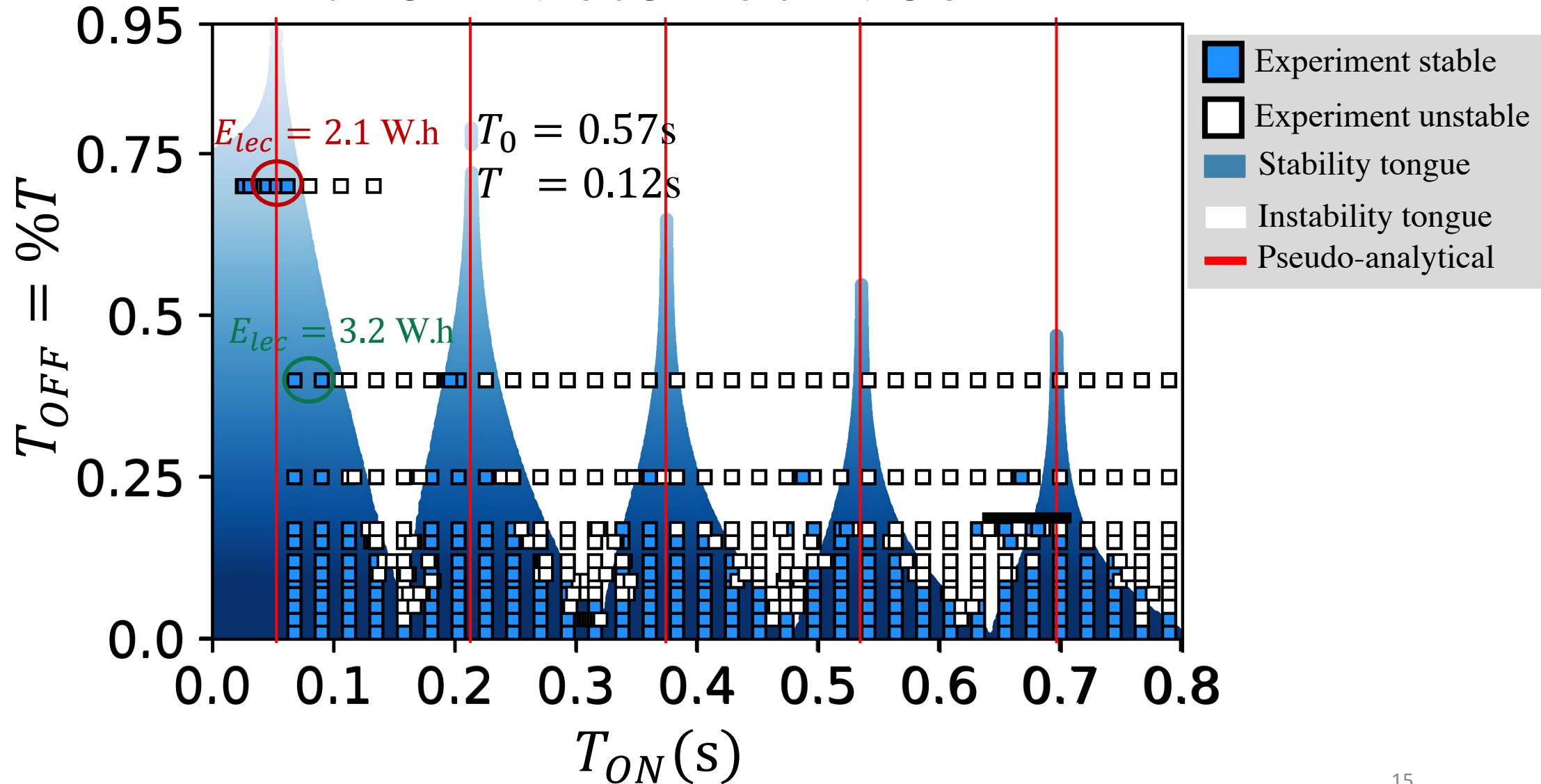
$$\left\{ \begin{array}{l} \frac{d^2\theta}{dt^2} - \omega^2(0)\theta(t) = 0 \text{ during } T_{OFF} \\ \frac{d^2\theta}{dt^2} + \omega^2(I)\theta(t) = 0 \text{ during } T_{ON} \\ (\dot{\theta}_0, \theta_0) \\ \text{Outside} = [-T_{OFF}/2, -T_{ON}/2] \cup [T_{ON}/2, T_{OFF}/2] \end{array} \right.$$

Boundary value problem [1]

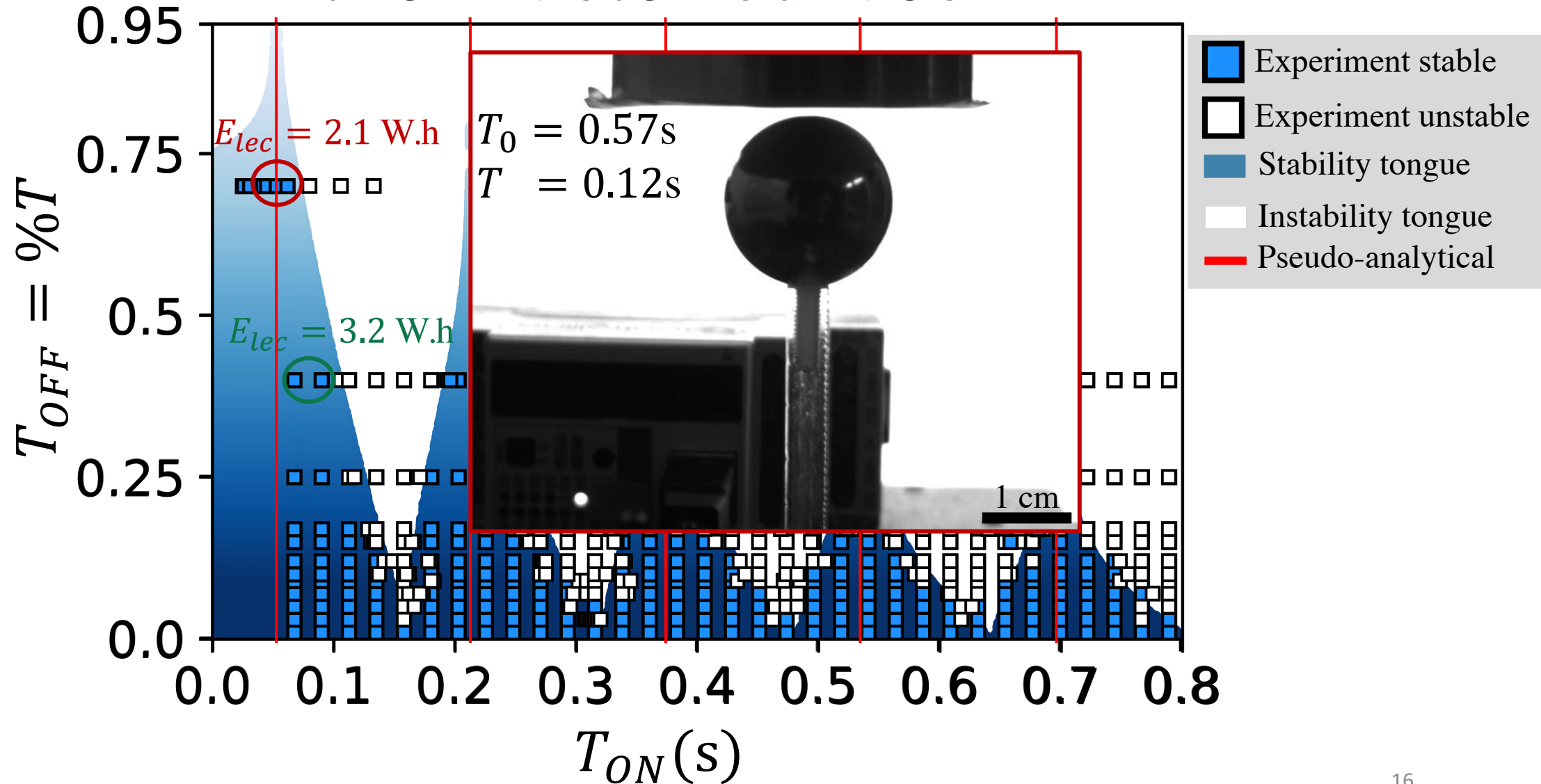
$$\left\{ \begin{array}{l} -\left[\frac{d^2}{dt^2} - \Delta\Omega^2 \right] \theta(t) = \omega^2(I)\theta(t), t \in \text{Outside} \\ -\left[\frac{d^2}{dt^2} + 0 \right] \theta(t) = \omega^2(I)\theta(t), t \in [-T_{ON}/2, T_{ON}/2] \\ \theta(-\infty) = \theta(\infty) = 0 \\ \text{Outside} = [-\infty, -T_{ON}/2] \cup [T_{ON}/2, +\infty] \text{ and } \Delta\Omega^2 = \omega^2(I) + \omega^2(0) \end{array} \right.$$

[1] A.Messiah. *Quantum mechanics*, 1, 1961.

Experimental validation of the master curves



Experimental validation of the master curves



Thank you for your attention