A Nonlinear Piezoelectric Shunt Absorber with 2:1 Internal Resonance

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Piezoelectric shunts



▷ Principle

- Piezoelectric patchs: mechanical / electrical energy conversion
- electric circuits:
 - → mechanical energy dissipation,
 - \rightsquigarrow counter vibrations.

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 - Resistive shunt: the energy is dissipated in the electrical resistance
 - · Resonant shunt: electric equivalent of a tuned mass damper

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Passive devices

- no external energy injected into the system (always stable)
- powered electronic components (semi-passive)

Resistive and resonant shunt responses



Resonant / resistive shunts [Thomas et al SMS 2012]

Good performance, but fully linear...

 \leadsto why not including nonlinearities in the shunt ?

Today's talk and state of the art



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- using 1:2 internal resonance for a saturation effect

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- Some works using 1:2 internal resonance exist in active control [Nayfeh & Pai teams, 1996-]
- Our solution is a semi-passive shunt

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> Other families of works on piezoelectric nonlinear dampers:

- Nonlinear Energy Sinks (NES) [Erturk team, SMS 2018], [Dekemele, Smart 2023]
- Nonlinear tuned vibration absorbers: a mirror of a primary nonlinear structure [Lossouarn, Raze, Kerschen, Deü 2018-]
- Synchronized Switch Damping [Guyomar team 2000-],...
- A non-smooth shunt (using a diode) [Shami, Thomas, Giraud-Audine, ND, 2023]

- $\left\{ \begin{array}{ll} \ddot{x}_1 + 2\mu_1 \dot{x}_1 + \omega_1^2 x_1 + \alpha_1 x_1 x_2 = 0 & \leftarrow \text{secondary oscillator} \\ \ddot{x}_2 + 2\mu_2 \dot{x}_2 + \omega_2^2 x_2 + \alpha_2 x_1^2 = f_2 \cos \Omega t & \leftarrow \text{primary oscillator} \end{array} \right.$

















- Below the threshold $f_2 < f_2^*$: linear uncontroled response;
- Above the threshold $f_2 > f_2^*$: nonlinear antiresonance + saturation of the amplitude thanks to a subharmonic transfer of energy

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Coupling a mechanical mode with an electrical circuit



Coupling a mechanical mode with an electrical circuit



• One eigenmode expansion + piezoelectric coupling + resonant circuit:

$$\boldsymbol{u}(t) = \boldsymbol{\Phi}_i q_i(t) \quad \Rightarrow \quad \begin{cases} \quad \ddot{q}_i + 2\xi_i \hat{\omega}_i \dot{q}_i + \hat{\omega}_i^2 q_i + \frac{\theta_i}{m_i C_{\text{pi}}} Q = \frac{F_i}{m_i} \cos \Omega t \\ \\ \quad \ddot{Q} + 2\xi_e \omega_e \dot{Q} + \omega_e^2 Q + \frac{\theta_i}{L C_{\text{pi}}} q_i + \frac{V_{nl}}{L} = 0 \end{cases}$$

 $q_i(t)$ mechanical modal coordinate; Q(t) electric charge; $(\hat{\omega}_i,\omega_e)$ mechanical and electrical natural frequencies: $\boxed{\omega_e=1/\sqrt{LC}\simeq\hat{\omega}_i/2}$

Coupling a mechanical mode with an electrical circuit



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- Linear piezoelectric coupling
- Nonlinear voltage source

 $\label{eq:Vnl} \begin{array}{l} \rightsquigarrow V_{nl} = \beta_1 Q^2 \Leftrightarrow \text{a nonlinear capacitor (no simple passive component)} \\ \rightsquigarrow V_{nl} = \beta_2 V^2 \text{: easier in practice (see after).} \end{array}$

Back to the canonical oscillators

• Expansion onto electromechanical modes (ψ_1, ψ_2) :

$$\begin{pmatrix} q_i \\ Q \end{pmatrix} = \Psi \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\Rightarrow \quad \left\{ \begin{array}{l} \ddot{x}_1 + 2\mu_1 \dot{x}_1 + \omega_1^2 x_1 + \Lambda_1 x_1^2 + \Lambda_2 x_1 x_2 + \Lambda_3 x_2^2 = 0 \\ \ddot{x}_2 + 2\mu_2 \dot{x}_2 + \omega_2^2 x_2 + \Lambda_4 x_1^2 + \Lambda_5 x_1 x_2 + \Lambda_6 x_2^2 = f_2 \cos \Omega t \end{array} \right.$$

with $q_i \simeq x_2$ (\simeq mechanical mode) & $Q \simeq x_1$ (\simeq electrical mode) because the piezoelectric coupling is often low.

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 \rightsquigarrow but also non-resonant terms of large value (Λ_1 in particular).

the non-resonant terms are responsible of a detuning of the nonlinear antiresonance as a function of the amplitude of forcing

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Effect of quadratic non resonant terms

detuning of the nonlinear antiresonance \Rightarrow loss of saturation of $x_2(t)$

Normal form transform & cubic terms

• From basic normal form theory, non-resonant quadratic terms are equivalent to cubic terms in the normal form:

$$\begin{cases} \ddot{x}_{1} + \omega_{1}^{2}x_{1} + g_{11}^{1}x_{1}^{2} + g_{12}^{1}x_{1}x_{2} + g_{22}^{2}x_{2}^{2} + \sum_{i,j,k} h_{ijk}^{1}x_{i}x_{j}x_{k} = 0 \\ \\ \ddot{x}_{2} + \omega_{2}^{2}x_{2} + g_{11}^{2}x_{1}^{2} + g_{12}^{2}x_{1}x_{2} + g_{22}^{2}x_{2}^{2} + \sum_{i,j,k} h_{ijk}^{1}x_{i}x_{j}x_{k} = f_{2}\cos\Omega t \\ \\ \\ \begin{pmatrix} x_{p} \\ \dot{x}_{p} \end{pmatrix} = \begin{pmatrix} r_{p} \\ \dot{r}_{p} \end{pmatrix} + \begin{pmatrix} \mathcal{P}_{p}^{(3)}(r_{i},\dot{r}_{i}) \\ \mathcal{Q}_{p}^{(3)}(r_{i},\dot{r}_{i}) \end{pmatrix} \\ \\ \\ \Rightarrow \begin{cases} \ddot{r}_{1} + \omega_{1}^{2}r_{1} + g_{12}^{1}x_{1}x_{2} + (h_{111}^{1} + A_{111}^{1})r_{1}^{3} + B_{111}^{1}r_{1}\dot{r}_{1}^{2} + \dots \\ \\ \dot{r}_{2} + \omega_{2}^{2}r_{2} + g_{11}^{2}x_{1}^{2} + (h_{112}^{2} + A_{111}^{1} - D_{112}^{2})r_{1}^{2}r_{2} + \dots \\ \\ \\ \\ \dot{r}_{oubic \ terms} \end{cases} = f_{2}\cos\Omega t \end{cases}$$

with A_{ijl}^k , B_{ijl}^k , D_{ijl}^k functions of quadratic **non-resonant** coefficients.

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Adding a **cubic term** in the shunt may help cancelling the effect of **quadratic non resonant** terms

Annihilation of the effect of non-resonant terms



We tune the cubic h_{ijl}^k terms to cancel the effect of the quadratic non-resonant terms on the **backbone curves** of the coupled 1:2 nonlinear modes:

 $\label{eq:explicit} \text{explicit formula} \ h^k_{ijl} = f(g^k_{ij}).$

Experiments 00000000

Saturation recovery



Quadratic & cubic shunt



- We add both quadratic and cubic NL terms in the shunt
- With only one degree of freedom (the alue of ceof. β_c), we are able to cancel only the largest quadratic non resonant term (g¹₁₁), leading to:

$$\beta_c = \frac{10}{9}\beta_c^2$$

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Proof of concept on a hydroelastic foil model



Nonlinear shunt tuned to damp the first bending mode (92 Hz)

Analog electronic circuit with multipliers







Perfect match !

Saturation effect



The cubic shunt clearly helps enhancing the saturation response range





Because of the saturation, above a certain threshold (tunable) the nonlinear shunt is **better** than the linear resonant (RL) shunt.

Conclusions & perspectives

- The use of a 2:1 internal resonance with a piezoelectric shunt to obtain a control device based on saturation is fully demonstrated, theoretically & experimentally with analog electronic components;
- An unexpected effect of **non resonant** quadratic terms (*detuning* and *quasiperiodic responses*) was cancelled thanks to **cubic terms** & **normal form theory**;
- All optimization results are detailed in publications. Especially, the figure of merit of the shunt, for the saturation amplitude, is ξ_e/(κβ_q) with ξ_e [-] electrical damping ratio, κ [-] piezoelectric coupling factor & β_c [V⁻¹] the quadratic voltage constant.

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