

8:00 - 8:05	Welcome
Plenary talks	
8:05 - 8:35	<p>Harnessing the surface tension of liquid metals: electrical actuation, Laplace barriers, and more.</p> <p>Aaron T. Ohta University of Hawai'i at Manoa</p>
8:35 - 9:05	<p>Smart droplets powered by chemical gradients: Chemotaxis, Phototaxis and Electrotaxis</p> <p>Larissa Florea, Trinity College Dublin, the University of Dublin</p>
9:05 - 9:10	Pause
Short Presentations	
9:10 - 9:20	<p>Acoustofluidic Embedded Microbubbles as Alternative to Common Microstructures</p> <p>Nino F. Läubli, University of Cambridge</p>
9:20 - 9:30	<p>3D micro fractal pipettes for capillary based robotic liquid handling</p> <p>Gilgueng Hwang, LIMMS-CNRS, Tokyo</p>
9:30 - 9:40	<p>How can beetles walk upside-down on smooth surfaces ? Elastocapillary adhesion control at the micrometer scale</p> <p>Tristan Gilet, University of Liege</p>
9:40 - 9:50	<p>Capillary-based Acoustofluidic End Effector for Robotics</p> <p>Daniel Ahmed, ETH Zurich</p>
9:50 - 10:00	<p>Manipulation of diamagnetic particles at the air-magnetic liquid interface</p> <p>Zoran Cenev, Aalto University</p>
10:00 - 10:10	<p>Toward a dynamic capillary solver for the robotic community</p> <p>Antoine Barbot, Femto-st</p>

10:10 - 10:40	Short Talks room discussions :Each of the short presentations' speakers will hold a room to further present/discuss his work with interested participants. Attendants can join one or several of these rooms to participate in the discussions.
Plenary talks	
10:40-11 :10	Acoustofluidics with bubbles Philippe Marmottant : LIPhy, CNRS-Universite Grenoble Alpes, France
11:10-:11 :40	Capillary micromanipulation and control of fluidic interface Quan Zhou , Aalto University, Finland
11:40-11:45	Concluding remarks